

Original instructions JSNY9 Safety interlock switch





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Table of Contents

1	Introduction	
	Scope	4
	Audience	4
	Prerequisites	4
	Special notes	4
2	Overview	5
	General description	5
	Safety regulations	5
	Function description	6
3	Connections	7
	Connection examples	8
4	Installation and maintenance	
	Installation precautions	14
	Maintenance	14
5	Operation	
6	Model overview	
	Accessories	16
7	Technical data	
	Dimensions	
8	EC Declaration of conformity	

1 Introduction

Scope

The purpose of these instructions is to describe the safety interlock switch JSNY9 and to provide the necessary information required for installation and operation.

Audience

This document is intended for authorized installation personnel.

Prerequisites

It is assumed that the reader of this document has knowledge of the following:

- Basic knowledge of ABB/Jokab Safety products.
- Knowledge of safety devices and safety locks.
- Knowledge of machine safety.

Special notes

Pay attention to the following special notes in the document:

Marning!

Danger of severe personal injury!

An instruction or procedure which, if not carried out correctly, may result in injury to the technician

or other personnel.

Danger of damage to the equipment! Caution!

An instruction or procedure which, if not carried out correctly, may damage the equipment.

NB: Notes are used to provide important or explanatory information.

2 Overview

General description

JSNY9 is a safety interlock switch with a locking function. The switch can only be actuated using a corresponding triple coded actuator and can be mounted in any direction (the switch head can be rotated 4x90 degrees). The actuation direction can be either linear or radial by using a specific actuator. The switch head can also be flipped upwards which allows both horizontal and vertical actuation directions. The holding force is 1500 N.

Additionally, the JSNY9 is tamper-proof (the switch cannot be actuated with screwdrivers, magnets or other tools).

The switch is well suited to lock a door or hatch to prevent access to machines:

- When the machine perform tasks that are not allowed to be stopped during the process, e.g. welding
- When the machine have long stopping time, e.g. paper machines with a long brake process
- To keep unauthorized persons away from a certain area

NB: To reach a high safety level when connected to the machine control system, it is recommended to use an ABB/Jokab Safety safety relay, Pluto safety-PLC or a Vital safety module with a Tina adaptor unit.

Warning! In order to maintain the safety level the actuator may only be procured and used as an integral part of the associated asfety switch.

Safety regulations

Warning! Carefully read through this <u>entire</u> manual before using the device.

The devices shall be installed by a trained electrician following the Safety regulations, standards and the Machine directive.

Failure to comply with instructions, operation that is not in accordance with the use prescribed in these instructions, improper installation or handling of the device can affect the safety of people and the plant.

For installation and prescribed use of the product, the special notes in the instructions must be carefully observed and the technical standards relevant to the application must be considered.

In case of failure to comply with the instructions or standards, especially when tampering with and/or modifying the product, any liability is excluded.



Function description

JSNY9 has 2 pairs (1NC + 1NO) contacts; the first pair change states when the actuator is inserted into the switch, and the second pair change states when the locking mechanism is in its locked position. The locking device is controlled through terminals E1-E2, and locking/unlocking characteristics is depending on the model.

There are two main models of the JSNY9, one with spring interlocking (JSNY9S) and one with solenoid interlocking (JSNY9M).

Spring interlocking (JSNY9S)

Spring interlocking (constant current circuit) means that the unit is locked as soon as the actuator is inserted into the switch, and power must be supplied to E1-E2 to unlock the device.

Solenoid interlocking (JSNY9M)

Solenoid interlocking (open circuit principle) means that power must be supplied to E1-E2 to lock the unit. This unlocks the door at power failure.





JSNY9S (spring interlocking)



JSNY9M (solenoid interlocking)



3 Connections

JSNY9 electrical connections



Contacts description:

Normal state when protection is active, i.e. when the actuator is inserted into the switch and the device is locked.

- **13-14** NO-contact. Closed when actuator is withdrawn.
- **21-22** NC-contact. Opened when actuator is withdrawn.
- E1-E2 Power for locking (M-type) / unlocking (S-type)
- **31-32** NC-contact. Opened when JSNY9 is unlocked.
- **43-44** NO-contact. Closed when JSNY9 is unlocked.

By design, locking is not possible unless the actuator is fully inserted into the actuator head. The contacts used to monitor the locking can therefore also be used to monitor the actuator position. The two NC-contacts (positive-opening NC) should be used to achieve the electrical dual-channel connection for the safety function.



Connection examples

Connection example: JSNY9S connected to safety relay RT6, actuator inserted and locked

A) Interlocking safety switch with manual reset and supervising of external relay contacts





System description / Application example

While the machine is running the movable guard is closed. The separate actuator is nested in the head of the safety switch. In this state the safety outputs are closed and unlocking is disabled. In case of e.g. maintenance the operator will need to gear into the machine behind the movable guard. In this case the operator will stop the machine first. The safety switch will keep the actuator locked until the dangerous machine has come to a safe stop. This can be achieved by using a suitable control device, such as a timer or lost motion detector. When the machine is stopped, unlocking is enabled. An unlock command (power supplied or power cut off, depending on type), will unlock the actuator and open the safety circuit. The safety relay will fall, and the machine cannot be started. The movable guard can now be opened. The positive-opening NC contacts should be used in the safety circuit and the auxiliary contacts can be used for signals or as a complement in the safety circuit to the safety relay, to achieve certain functions.

The contacts for monitoring the position of the actuator are operated directly by the actuator in order to register the position of the guard directly. The contacts for monitoring the locking function are directly connected with the locking bolt. A failure of the locking function can be detected by the safety relay. The design of the locking is of such a kind that the locking cannot be activated unless the actuator is completely inserted into the head of the safety switch. Thus the contacts for monitoring the locking function can also be used to monitor the position of the movable guard. The possibility to monitor both contacts (movable guard and locking function) separately leads to a dual channel mode.

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4 Installation and maintenance

JSNY9 is easily fitted on the ABB/Jokab Safety Quick-Guard fencing system using special brackets found in the "Accessory"-section below.

The actuation direction can be chosen either linear or curved, using the appropriate actuator.

Actuators and installation



Standard actuator

For sliding doors and hinged doors with actuating radius >400 mm. Head position: 0°, 90°, 180°, 270°.

NB: Washers for M4 with outer diameter ø12 mm MUST be used to achieve form-locking!

Universal actuator

For hinged doors with actuating radius >150 mm

Head position: 0°, 90°, 180°, 270°.

NB: Fixing holes ø 5.5 mm symmetric in position with X- or Z-axis.

Actuator mounting

2 x M5 DIN 912 or EN ISO 1207

 $M_{max} = 4 Nm$

Universal actuator pre-adjustment

When using the flexible (universal) actuator, proper pre-adjustment of the actuator using the internal hexagon screws are necessary to avoid unnecessary shearing forces on the actuator.

Align the actuator with the machine guard so that opening or closing the machine guard does not apply lateral force to the actuator head. Verify by opening and closing the guards several times.

Actuator head direction



Actuator head rotation



Horizontal directions

Vertical directions

 20^{+10}_{-0}



Securing the actuator head



Marning!

To prevent manipulation of the actuator head the pre-fitted torx/slot-head screw should be replaced with the supplied tamper-proof screw.

Exceeding the specified torque of 0.9 Nm or an actuator assembly which causes objectionable forces in the cross plane will result in damage to the actuating parts of the switch gear. This will lead to the loss of the safety function and thus can lead to severe or even fatal accidents to the operator.

Make sure that the head is properly attached to the switch body. A misaligned or loose head can lead to loss of the safety function.

Vibrations and other forces acting on the security screw might cause the screw to loosen over time, which will lead to the loss of the safety function. At regular intervals, make sure the security screw is tightened correctly.





To install a cable gland in the M20 threaded connector:

Release the snap-shut terminal lid with a screwdriver and screw the cable gland into the chosen entry. This will "breakout" the blind hole; remove the plastic disk when detached.

To connect wires to the terminal block:

- Insert screwdriver (blade width 2.5 mm) in lower opening.
- 2) Turn 45 degrees according to figure.
- Insert wire (0.5 1.5 mm2 cross-section) in upper opening. Release the screwdriver and pull the wire to make sure it is properly connected.





- 1) Loosen the security screw.
- 2) To unlock, rotate internal hexagon screw 90°.

The actuator can now be pulled out.

To return to safe state, rotate the internal hexagon screw backwards.

3) Tighten the security screw and seal with lacquer.

A Warning!

Auxiliary release shall only be operated during installation or in case of failure of the normal "Power to unlock". Auxiliary release shall be sealed with lacquer after completed installation of the safety switch. **BIOKAB SAFETY**

Installation precautions

- The safety switch may not be used as a mechanical stop!
- Make sure that the head is properly attached to the switch body. A misaligned or loose head can lead to loss of the safety function.
- The device must be mounted on a plane surface.
- Secure the screws against self-loosening.

Marning! All the safety functions <u>must</u> be tested before starting up the system.

Maintenance

Marning!

It is very important that the security screw holding the actuator head in place is checked regularly for self-loosening, and is retightened correctly if necessary. Do not over-tighten the screw as it will cause damage to the actuating parts of the switch gear.

The safety functions and the mechanics shall be tested regularly, at least once every year to confirm that all the safety functions are working properly (EN 62061:2005).

In order to maintain the safety level, regular inspections for tear and wear, as well as fixing and alignment of switch, actuator, brackets, doors etc should be carried out.

In case of breakdown or damage to the product, contact the nearest ABB/Jokab Safety Service Office or reseller. Do not try to repair the product yourself since it may accidentally cause permanent damage to the product, impairing the safety of the device which in turn could lead to serious injury to personnel.

5 Operation

JSNY9 S-types

Spring to lock

JSNY9 S-types "spring to lock", i.e. the device is locked as soon as the actuator is inserted into the actuator head. By design, the locking cannot be activated unless the actuator is completely inserted into the actuator head.

Power to release

JSNY9 S-types require "power to release", i.e. the device requires power supplied to E1-E2 in order to unlock the actuator when inserted into the actuator head.

Contact states

The internal contacts (2 pairs of 1 NC + 1 NC, "normal" state when machine is allowed to run) switch states when the actuator is inserted and when the devices is locked. The first pair switches states as soon as the actuator is inserted into the actuator head, and the second pair switch states when the device is locked, i.e. when no power is supplied to E1-E2. Since the locking cannot be activated unless the actuator is completely inserted into the actuator head, the contacts used to monitor the locking can also be used to monitor the position of the movable guard.

JSNY9 M-types

Power to lock

JSNY9 M-types require "power to lock", i.e. the device requires power supplied to E1-E2 in order to lock the device after the actuator has been inserted into the actuator head. By design, the locking cannot be activated unless the actuator is completely inserted into the actuator head.

Spring to release

JSNY9 M-types "spring to release", i.e. the device unlocks as soon as the power to E1-E2 is cut off.

Contact states

The internal contacts (2 pairs of 1 NC + 1 NC, "normal" state when machine is allowed to run) switch states when the actuator is inserted and when the devices is locked. The first pair switches states as soon as the actuator is inserted into the actuator head, and the second pair switch states when the device is locked, i.e. when power is supplied to E1-E2. Since the locking cannot be activated unless the actuator is completely inserted into the actuator head, the contacts used to monitor the locking can also be used to monitor the position of the movable guard.



6 Model overview

Туре	Article number	Description
JSNY9S 24 VUC	2TLJ020036R4400	JSNY9 safety switch with spring locking (power to lock). 24 V DC/AC.
JSNY9M 24 VUC	2TLJ020036R4500	JSNY9 safety switch with solenoid locking (power to unlock). 24 V DC/AC.

Accessories

Note that all brackets come with nuts and screws for use with ABB/Jokab Safety Quick-Guard fencing system. For further information, contact your local ABB/Jokab Safety sales office.

Туре	Article number	Description
Spare part	2TLJ020033R0300	Lid packing for JSNY9.
Spare part	2TLJ020033R0400	Security screw for JSNY9 head. PTS 3x16 one-way screw.
JSM D4F	2TLJ040033R3000	Brackets for sliding door.
JSM D4C	2TLJ040033R1600	Brackets for hinged door.
JSNY8/9N1	2TLJ020032R0400	Standard actuator for JSNY8/9. Fixed, for actuating radius >400 mm.
JSNY8/9N2	2TLJ020032R0500	Universal actuator for JSNY8/9. Flexible, for actuating radius >150 mm.



JSM D4C Brackets for hinged door Article number: 2TLJ040033R1600



JSM D4F Brackets for sliding door Article number: 2TLJ040033R3000



JSNY8/9N1 Standard actuator Article number: 2TLJ020032R0400



JSNY8/9N2 Universal actuator Article number: 2TLJ020032R0500

7 Technical data

Manufacturer	
Address	ABB AB / JOKAB SAFETY Varlabergsvägen 11 SE-434 39 Kungsbacka Sweden
Electrical characteristics	
Utilization category	AC15 230 V/2.5 A
Rated impulse withstand voltage (U_{imp})	2.5 kV
Rated insulation voltage (U _i)	250 V
Rated thermal current (I_{th})	5 A
Total current max (4 contacts)	4 x 2.5 A
Short circuit protection (fuse)	4 A slow-blow fuse
Solenoid	
Duty cycle	100 % ED (at E1;E2)
Temperature class	F (155°C)
Inrush power consumption	12 VA (0.2 s), UC-type
Permanent power consumption	4.4 VA, UC-type
Switch operation (permanent)	Max 600/h
Operating voltage	24 V DC or AC, UC-type
Switch-on delay	Max 250 ms
Mechanical data	
Material	Enclosure: PA 6 GV (UL94-VO) Cover (lid): PA 6 GV (UL94-VO) Actuating mechanism: PA 6 GV (UL94-VO)/Zn-GD Actuator: Steel/PA/Zn-GD
Colour	Black, yellow label
Ambient temperature	-25+70°C
Holding force (max)	Locked: 1500 N (GS-ET 19, see note below) Unlocked: 27 N
Switching function/contact configuration	Locking: 1 NO + 1 NC Movable guard: 1 NO + 1 NC
Mechanical life	1 million operations (at max 600 operations/h)
Actuating radius (min)	Standard actuator: R _{min} = 400 mm Universal actuator: R _{min} = 150 mm
Actuating velocity (max)	V _{max} = 0.5 m/s
Size	See drawings below
Weight	Approx 0.3 kg
Mounting	4 x M5 screws ISO1207/DIN 84 Max. torque: M = 2 Nm ISO4762/DIN 912



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Mechanical data

Cable size (max)	Max 1.5 mm ² stranded wire	
Terminals	10 cage clamp elements	
Cable entries	3 x M20x1.5	
Protection class	IP67 according to IEC/EN 60529	
NB: 1 holding force test cycle according to GS-ET 19: a) steady increase of holding force 200 N/s b) keep max holding force for 5 s. c) safety factor 1.3		
Safety / Harmonized Standards		
Conformity	European Machinery Directive 2006/42/EC C EN ISO 12100-1:2003+A1:2009, EN ISO 12100-2:2003+A1:2009, EN 954-1:1996/EN ISO 13849-1:2008, EN 1088+A2:2008, EN 60204-1:2006+A1:2009 VDE 0660 T100, EN 60947-1, VDE 0660 T200, EN 60947-5-1, GS-ET 19	
EN ISO 13849-1	Category 1 B10 _d : 2,000,000	
Certificates	CSA	

NB: A single JSNY9 can achieve performance level PL c according to EN ISO 13849 if used correctly with an ABB/Jokab Safety safety relay, Pluto safety-PLC or Vital safety module. If two JSNY9-switches are used for the same safety function, a performance level up to PL e can be achieved. Refer to EN ISO 13849 for details on how to achieve this if necessary.



Dimensions

JSNY9 dimensions



Actuator dimensions





JSNY8/9N1 Standard actuator

NB: All measurements in millimetres.





JSNY8/9N2 Universal actuator

19



8 EC Declaration of conformity



EC Declaration of conformity (according to 2006/42/EC, Annex 2A)

We ABB AB JOKAB Safety Varlabergsvägen 11 SE-434 39 Kungsbacka Sweden

the Directive 2006/42/EC

Authorised to compile the technical file ABB AB JOKAB Safety Varlabergsvägen 11 SE-434 39 Kungsbacka Sweden

Product

Lockable safety interlock switch JSNY8 JSNY9 Used harmonized standards

EN ISO 12100-1:2010, EN ISO 13849-1:2008, EN 1088+A2:2008, EN 60204-1:2006+A1:2009

declare that the safety components of ABB AB manufacture with type

designations and safety functions as listed below, is in conformity with

Jesper Kristensson PRU Manager Kungsbacka 2011-12-06

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ABB AB / JOKAB SAFETY Varlabergsvägen 11, SE-434 39 Kungsbacka, Sweden

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